

CLAIMS

1. A method for attenuating sound in a duct, the sound to be attenuated being detected in the method by means of a detector (2) and the attenuation being performed by means of two successive actuator elements (3, 4), characterized in that sound is attenuated by means of two successive monopole elements (3, 4) in such a way that both elements (3, 4) function as a dipole approximation and also produce a monopole radiation needed, a dipole control signal being fed to both elements (3, 4) at a phase shift which is 180° between the two elements and a monopole control signal being fed to the elements (3, 4) cophasally.

2. A method according to claim 1, characterized in that the control signal of the first actuator element (3) is

$$q_1 = \frac{1}{2}(a/jkd - b/2)q_i$$

and the control signal of the second actuator element (4) is

$$q_2 = -\frac{1}{2}(a/jkd + b/2)q_1$$

where

j is an imaginary unit;

k is a wave number = ω/c_0 ;

ω is an angular frequency:

c_s is sound velocity in a medium;

d is a distance between the actuator elements (3, 4);

q_i is the sound pressure to be attenuated, located at the centre of the actuator elements (3, 4), and converted to a volume velocity quantity;

a is a constant or a dipole part control function; and
b is a constant or a monopole part control function.

3. A method according to claim 2, characterized in that a is a dipole part control function and b is a monopole part function such that

kd/2

$$a = \frac{\dots}{\sin(kd/2)}$$

and

$$b = \frac{1}{\cos(kd/2)}$$

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4. A method according to claim 2 or 3, **characterized** in that in the control signals (q_1, q_2) of the elements the impact of the imaginary unit is determined by using an integrator.

5. An equipment for attenuating sound in a duct, the equipment comprising a detector (2) for detecting the sound to be attenuated and two successive actuator elements (3, 4) for producing a sound attenuating counter-sound, **characterized** in that the actuator elements (3, 4) are monopole elements which are arranged to function as a dipole approximation and to also produce a necessary monopole radiation and that the equipment 10 comprises means for feeding a dipole control signal to both elements (3, 4) at a phase shift which is 180° between the two elements and for feeding a monopole control signal to the elements (3, 4) cophasally.

15. An equipment according to claim 5, **characterized** in that the control signal of the first actuator element (3) is

$$q_1 = \frac{1}{2}(a/jkd - b/2)q_i,$$

and the control signal of the second actuator element (4) is

$$q_2 = -\frac{1}{2}(a/jkd + b/2)q_i,$$

where

20 j is an imaginary unit;

k is a wave number = ω/c_0 ;

ω is an angular frequency;

c_0 is sound velocity in a medium;

d is a distance between the actuator elements (3, 4);

25 q_i is the sound pressure to be attenuated, located at the centre of the actuator elements (3, 4), and converted to a volume velocity quantity;

a is a constant or a dipole part control function; and

b is a constant or a monopole part control function.

30 7. An equipment according to claim 6, **characterized** in that a is a dipole part control function and b is a monopole part function such that

$$kd/2$$

$$a = \frac{1}{\sin(kd/2)}$$

and

$$35 \quad b = \frac{1}{\cos(kd/2)}.$$

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